

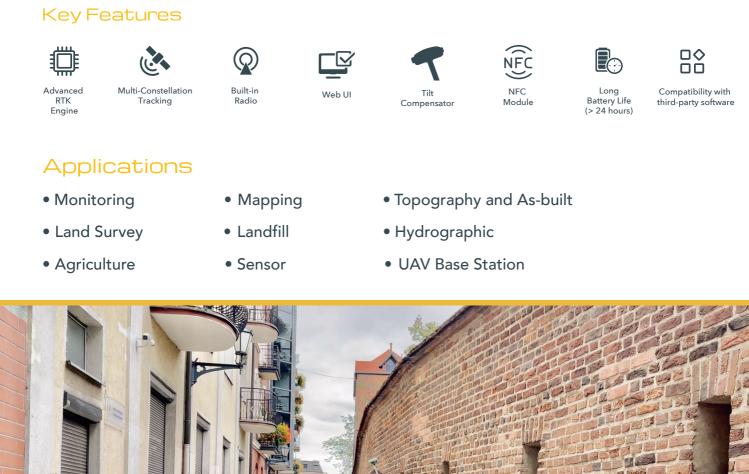






Made by Sweden

SatLab Freyja GNSS RTK is a progressive receiver that creates a new RTK experience for land surveyors. With its comprehensive features, it can perfectly handle the situations encountered in all kinds of surveying work, minimizing the burden from the physicality and extending the functionality of fieldwork. By increasing productivity by 25%, Freyja offers an accurate and efficient solution.





Handiness and Convenience

Refinement of design makes it rugged and compact with only 770g. A more durable battery ensures operating time reaches more than 24 hours. Durability and portability are optimized for surveyors who carry them around a lot in the fieldwork.

Accuracy and Precision

Matured RTK technology promises positioning reliability. New GNSS Antenna, full-constellation and all satellite signal tracking technology lay the solid foundation-precision of fieldwork.

Adaptability and Stability

Equipped with the latest tilt compensation algorithm and built-in high-performance 9-axis Inertial Measurement Unit (IMU), the measurement for hard-to-reach points is simple but precise with the high-performance tilt survey. Quality results are guaranteed even if you lose the signal while under extreme circumstances with great anti-interference ability.











TECHNICAL SUPPORT Satlab offers online resources and a professional support network available worldwide.

FREYJA GNSS Receiver

Data Specifications

Data Specifications	
GNSS Signal Tracking [®]	GPS (L1C/A, L1C, L2P(Y), L2C, L5) BDS (B11, B21, B31, B1C, B2a, B2b) GLONASS (L1, L2, L3) Galileo (E1, E5a, E5b, E6) QZSS (L1, L2, L5, L6*) NavIC(L5) SBAS(L1, L2, L5) PPP(B2b-PPP, Galileo E6-HAS)
No. of Channels	1408
High-precision static GNSS Surveying Static and Fast Static Post Processing Kinematic (PPK / Stop & Go)	H:2.5mm + 0.1 ppm RMS / V:3.5mm + 0.4 ppm RMS H:2.5mm + 0.5 ppm RMS / V:5mm + 0.5 ppm RMS H:8mm + 1 ppm RMS / V:15mm + 1 ppm RMS Initialization time: Typically 10 min for base and 5 min for rov Initialization reliability: Typically>99.9%
PPP	H:10cm / V:20cm
Code Differential GNSS Positioning	H:±0.25m+1ppmRMS / V:±0.5m+1ppmRMS SBAS:0.5m(H), 0.85m(V)
Real Time Kinematic (RTK)	H:8mm+1ppm RMS / V:15mm+1 ppm RMS Initialization time: Typically <10 s Initialization reliability: Typically > 99.9%
Positioning rate Time to first Fix Hi-Fix [®] Tilt Survey Performance [®]	1Hz, 5Hz and 10Hz Cold start:< 45s Hot start:< 30s Signal re-acquisition:< 2 s H:RTK+10mm / minute RMS / V:RTK+20mm / minute RMS Additional horizontal pole-tilt uncertainty typically less than 8mm +0.7 mm / °tilt (0° ~ 60°)
COMMUNICATION I/O Interface WiFi Bluetooth NFC Internal UHF Radio	1 × USB type C port; 1 × SMA antenna port Frequency 2.4GHz, Supports 802.11 b/g/n 4.2 / 2.1+EDR, 2.4GHz Near Field Communication for device touch pairing Frequency: 410-470MHz Channel: 116 (16 scalable) Transmitting power: 0.5W / 1W / 2W adjustable Working Range: Typically 3~5km, optimal 8~15km Supports multi-communication protocols: HI-TARGET, TRIMTALK450S, TRIMMARK III, TRANSEOT, SATEL-3AS, etc.
ELECTRICAL Internal battery [®]	Internal 7.2V / 6900mAh lithium-ion rechargeable battery RTK Rover (UHF/Cellular): up to 24 hours*
External power	Charging:using standard smartphone chargers or external power banks.(Support 5V 2.8A Type-C USB external charging
PHYSICAL Weight Dimensions (W x H) Operation temperature Storage temperature Humidity Water/dustproof	≤ 0.8kg(includes battery) 132mm×67mm -30°C to +70°C -40°C to +80°C 100% non-condensing IP67 dustproof, protected from temporary immersion to
Free fall	depth of 1.0m (3.28ft) Designed to survive a 2m(6.56ft) natural fall onto concrete
CONTROL PANEL LED Lamp Physical button	Satellite, Signal, Power 1
SYSTEM CONFIGURATION Storage Output rate Output format Static data format Network Mode Real Time Kinematic (RTK)	8GB ROM internal storage 1Hz-20Hz ASCII: NMEA-0183 GNS, Rinex VRS, FKP, MAC; supports NTRIP protocol CMR, RTCM 2.x, RTCM 3.x

*Description and Specifications are upgrade. 1.025S L6 can be provided by firmware upgrade. 2.The measurement accuracy, precision, reliability and initialization time depend on various factors, including tilt angle, number of satellites, geometric distribution, observation time, atmospheric conditions and multi-path validation, etc. The data are derived under normal conditions. 3.Accuracies are dependent on GNSS satellite availability. Hi-Fix Positioning ends after 5 minutes without differential data.Hi-Fix is not available in all regions, check with your local sales representative for more information. 4.Irregular operations such as rapid rotation and high-intensity vibration may affect the inertial navigation accuracy. 5.The battery operating time is related to the operating environment, operating temperature and battery life.



Headquarters: GEOSOLUTION I GÖTEBORG AB Stora Åvägen 21, 436 34 ASKIM, Sweden

- **Regional Offices:**
- Warsaw, Poland Jičín, Czech Republic Ankara, Turkey Scottsdale, USA Singapore Hong Kong, China Dubai, UAE

www.satlab.com.se